

Chair for Network Architectures and Services – Prof. Carle Department of Computer Science TU München

Discrete Event Simulation

IN2045

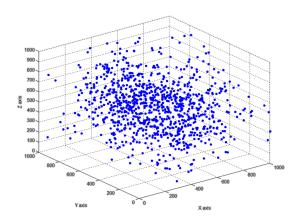
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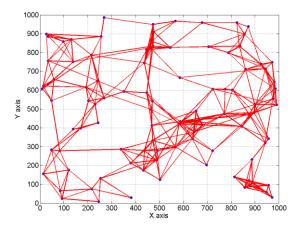
Chair for Network Architectures and Services Department of Computer Science Technische Universität München http://www.net.in.tum.de





- Point Fields
 - Generation of Point Fields
 - Constant / Variable Number of Points
 - Rectangle / Arbitrary Area
 - Homogeneous Point Fields
 - Inhomogeneous Point Fields
 - Poisson Field
 - Matern Cluster Field
- Random Graphs
 - Generation of Random Graphs
 - Probabilistic Model
 - Waxman Model
 - Implementation Issues:
 - Adjacency Matrix/List
 - Incidence Matrix
 - Scale-free Graphs

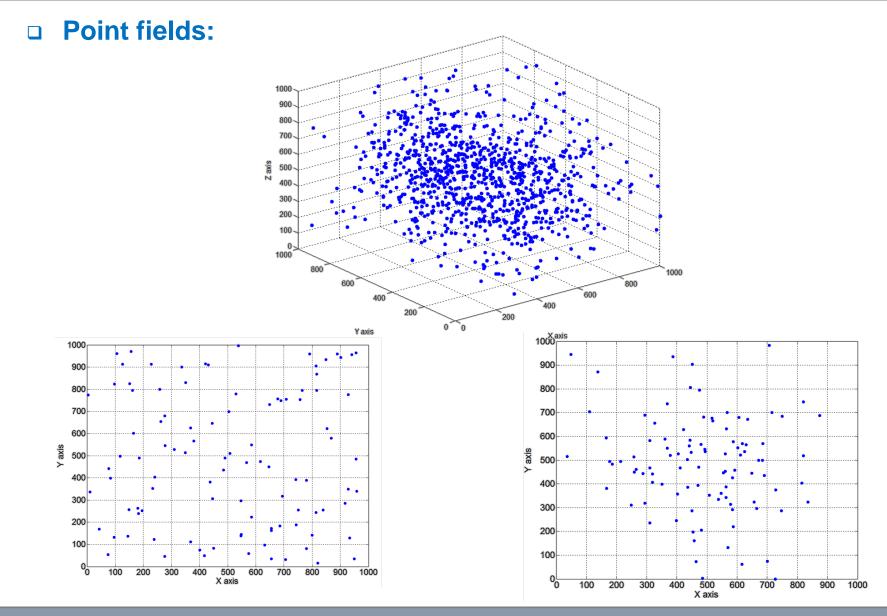






Point Fields



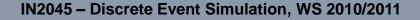


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Point field:

- Two dimensional random process
- Spatial distribution of objects in two dimensional space
 - Seismology (epicenters of earthquakes)
 - Plant ecology (position of trees or other plants)
 - Epidemiology (home locations of infected people)
 - Zoology (burrows or nests of animals)
 - Astronomy (location of stars)
 - Telecommunication (spatial distribution of mobile users)
- The development of many system parameters is influenced by the spatial distribution of the simulated objects





Point fields with a constant number of points (rectangle):

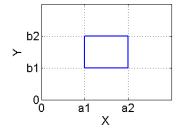
Task:

Generate a homogeneous point field with n points in a rectangle which is given by $(a_1,b_1),(a_1,b_2),(a_2,b_1),(a_2,b_2)$

- Algorithm:
 - for i = 1:n
 - Generate random variable $z1 \sim U(0,1)$
 - Generate random variable $z_2 \sim U(0,1)$

- Point
$$(x, y) = (a_1 + z_1 \cdot (a_2 - a_1), b_1 + z_2 \cdot (b_2 - b_1))$$

end







Point fields with a variable number of points (rectangle):

- F size of the rectangle
- *E*[X] average number of points in F

•
$$\lambda = \frac{E[X]}{F}$$
 - intensity of the point field

- X discrete random variable which describes the number of points in the rectangle
- Generate a homogeneous point field with X points



Binomial – Point Field

Binomial distributed number of points

$$P(X = i) = {\binom{n}{i}} p^{i} (1 - p)^{n - 1} , \quad p = \frac{E[X]}{n}$$

Upper bound: n

Poisson – Point Field

Poisson distributed number of points

$$P(X=i) = \frac{(\lambda F)^{i}}{i!} e^{-\lambda F} , \ \lambda = \frac{E[X]}{F}$$

- Upper bound: no upper bound !!!
- Generation: c.f. point fields with variable number of points



Poisson – Point Field

- Optimized Generation:
 - 1. Generate x-coordinates by using a one dimensional Poisson process

in (a₁, a₂) with rate
$$\lambda^* = \frac{E[X]}{a_2 - a_1}$$

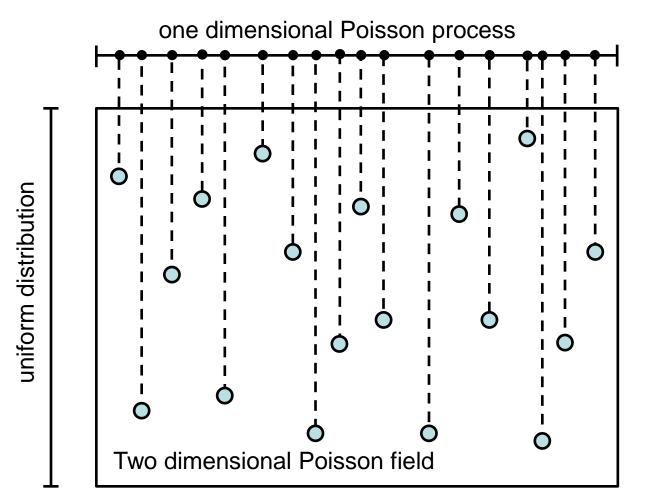
Note that the one dimensional process specifies the number of points in the point field.

2. Generate the y-coordinates according to a uniform distribution in the interval (b₁, b₂)



Poisson – Point Field

Optimized Generation:





D Point fields with a variable number of points in an arbitrary area:

- Problem:
 - Area has arbitrary shape and size F*
 - Average number of points in F* = E[X*]

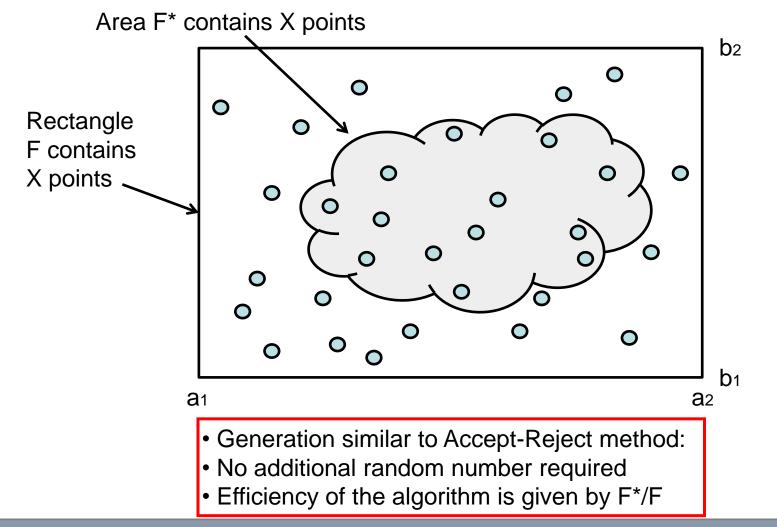
• Point intensity in F*:
$$\lambda^* = \frac{E[X^*]}{F^*}$$

- Previously introduced algorithms only work for rectangles
- Solution:
 - Generate a rectangle such that the arbitrary area F* fits in the rectangle
 - Generate points in the rectangle which includes the area F* until the desired number of points are in the area F*



D Point fields with a variable number of points in an arbitrary area:

Optimized Generation:





Inhomogeneous point fields

- Characteristics
 - Point intensity $\lambda(x, y)$ depends on the position

• Maximum
$$\lambda_{\max} = \max_{(x,y)} (\lambda(x,y))$$

• Point intensity in F*: $\lambda^* = \frac{E[X^*]}{F^*}$

- Generation:
 - Calculate E[x] by integrating $\lambda(x, y)$ over F
 - Choose RV X according to E[x]
 - Repeat the following three steps until X points are generated

2. Choose a random number z \square RV Z ~ U(0,1)

3. Accept if
$$z \leq \frac{\lambda(x, y)}{\lambda_{\max}}$$
 , otherwise reject



Inhomogeneous / homogeneous point fields

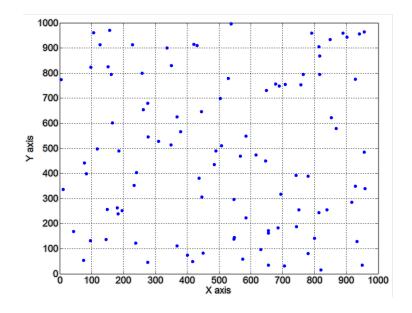
Impact of the chosen distribution on the point field

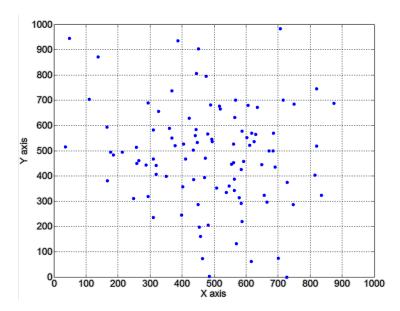
Example 1:

- \Box x axis uniform distributed
- □ y axis uniform distributed

Example 2:

- \Box x axis normal distributed
- □ y axis normal distributed







Cluster point fields

- Idea:
 - Generate a point field with low density where each point represents a parent point
 - Generate a homogeneous Poisson field with intensity λ_e around parent points which represent the centre of the clusters
- Matern cluster field:
 - Create a homogeneous Poisson field around each parent point with radius R
 - Average number of points in each circle is given by E[X]
 - Intensity in each field around a parent point $\lambda = \frac{E[X]}{F} = \frac{E[X]}{\pi R^2}$



Cluster point fields

Matern cluster field:

A Matern cluster field can be generated in different ways

• 1. Generation: Accept-Reject method

inefficient due to the high number of circle shaped Poisson field

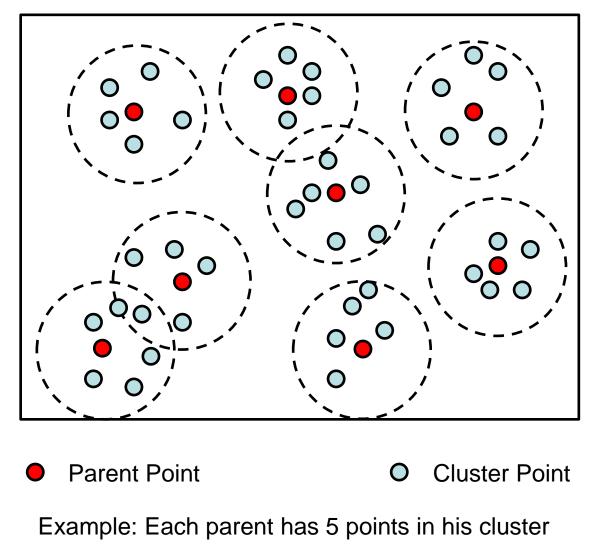
- 2. Generation: Usage of polar coordinates (φ, r)
 - Generate uniform distributed coordinate $\varphi \in [0, 2\pi)$
 - Generate distance $r \in [0, R($ according to the following density function (2r)

$$f(r) = \begin{cases} \frac{2r}{R^2} & r \le R \\ 0 & \text{sonst} \end{cases}$$

- Uniform distribution of r results in a decrease of the intensity towards the border of the circle
- The rectangle for parent point generation has to be smaller than the Matern cluster field in order to mitigate border effects



Matern cluster field





Random Graphs



Random Graphs

A graph is an abstract representation of a set of objects where pairs of objects can be connected by links.

- Graph G = (V, E)
- V: Vertices/Nodes = Router
- E: Edges = Links
 - $e = \{u, v\} \in V \times V$
 - Undirected bidirectional
 - Directed unidirectional
- Node degree $\delta(v)$, $v \in V$ Number of edges that are connected with v
- Average node degree: $\delta^* = 2 \cdot |E| / |V|$
- In-degree $\delta^{-}(v)$: number of edges that point to node v
- Out-degree $\delta^+(v)$: number of edges that point away from node v
- Distance $d_G(u,v)$: shortest path between two vertices in the graph
- Network diameter: longest path between two vertices in the graph
- K-(edge/vertex)-connected: A graph is called k-connected if at least k edges have to be removed in order to partition the graph



Random Graphs with predefined characteristics

- Generate a predefined number of nodes in a plane (point field)
- Connect the nodes in the network by applying one of the following models
 - 1. Basic model(1/2):
 - Generation:

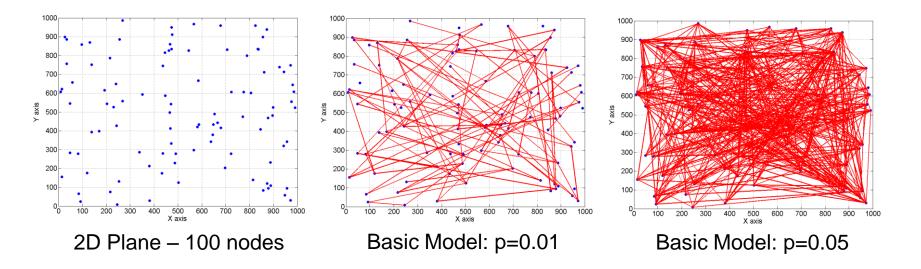
Generate an edge between two nodes with probability p

- Advantage:
 - » Fast and simple
- Disadvantage:
 - » Number of links per node varies
 - » Average node degree only depends on the number of nodes
 - » Connectivity between two nodes does not depend on the distance between them
 - » Does not guarantee full connectivity of the network
 - » Does not fit for large networks



Random Graphs with predefined characteristics

1. Basic model(2/2):



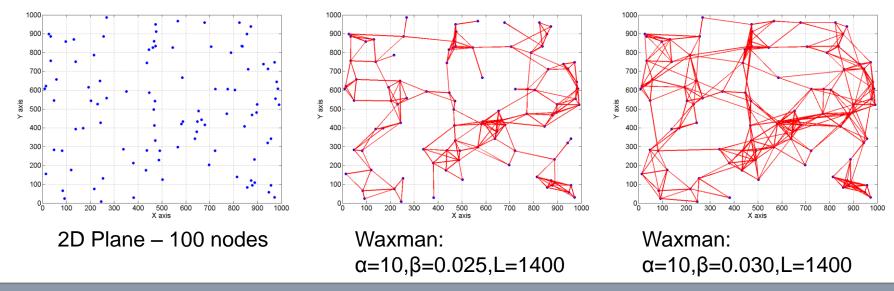
Random Graphs

Random Graphs with predefined characteristics

- 2. Waxman model:
 - Connectivity between two nodes becomes more likely the shorter the distance between them
 - Probability that two nodes are connected is given by

$$P(u,v) = \alpha \cdot e^{\frac{-d}{\beta \cdot L}}$$
 with $\alpha > 0, \beta \le 1$

- » D: Euclidean distance between the two nodes
- » L: The maximum distance between two nodes



Random Graphs

Random Graphs with predefined characteristics

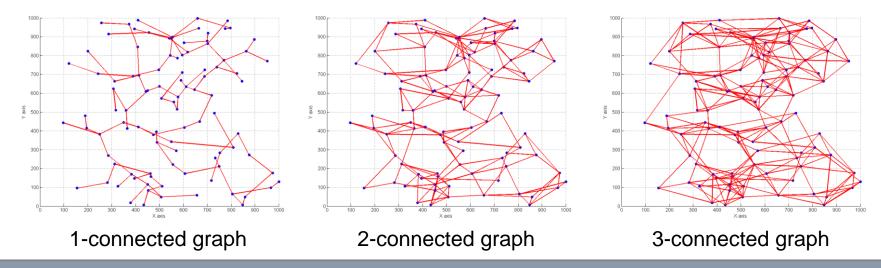
3. Node degree model:

Problem: Generate a random graph where nodes have at least a minimum degree but less than a maximum degree

- These graphs are usually generated in an iterative way by adding

$$\left|E\right| = \frac{\delta^* \cdot \left|V\right|}{2} \quad \text{edges}$$

k-connected topologies are often used to make the network more resilient against node failures





- Basic operations:
 - add / remove (Edge e / Vertex v)
 - find (Edge e / Vertex v)
 - getVertices (Graph g)
 - getEdges (Graph g)
- Complex operations:
 - getDegree (Vertex v)
 - isReachable (Vertex src, Vertex dst)
 - shortestPath (Vertex src, Vertex dst)
 - isComplete (Graph g)
 - isConnected (Graph g)
 - totalWeight (Graph g)

- Degree of node v
- True if a path exists from src to dst, false otherwise.
- True if all nodes have max degree.
- True if isReachable returns true for all nodes.
- Sum of all weights.
- getOneHopNeighbors (Graph g, Vertex v) List of all direct neighbors.

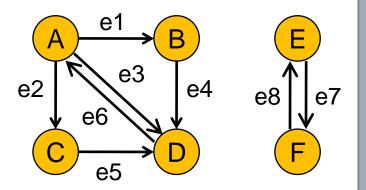


- Matrix structures:
 - Adjacency matrix:

Is an n by n matrix A where n is the number of vertices |V| in the graph. Two vertices i and j are connected with an edge pointing from vertex I to vertex j if the element $a_{i,j}$ is 1, otherwise 0.

Example:

Src Vertex / Dst Vertex	Α	В	С	D	Е	F
Α	0	1	1	1	0	0
В	0	0	0	1	0	0
С	0	0	0	1	0	0
D	1	0	0	0	0	0
E	0	0	0	0	0	1
F	0	0	0	0	1	0



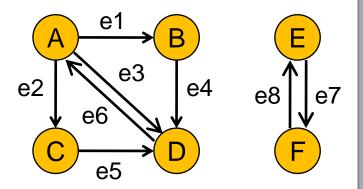


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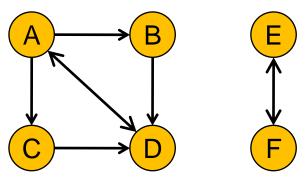
Example:

Src Vertex / Dst Vertex	Α	В	С	D	Е	F
Α	0	1	1	1	0	0
В	0	0	0	Out	goir	ng
С	0	0	0	1	0	0
D	1	0	0	ø	0	0
E	Incoming 0 🔊 1				1	
F	0	0	0	0	1	8





- Matrix structures:
 - Adjacency matrix:



Out-degree / in-degree

Src Vertex / Dst Vertex	Α	В	С	D	Е	F	Out-degree
Α	0	1	1	1	0	0	3
В	0	0	0	1	0	0	1
С	0	0	0	1	0	0	1
D	1	0	0	0	0	0	1
E	0	0	0	0	0	1	1
F	0	0	0	0	1	0	1
In-degree	1	1	1	3	1	1	0

Out-degree and in-degree of each vertex is represented by the sum of the corresponding row or column of the adjacency matrix



- Matrix structures:
 - Adjacency matrix:
 - Characteristics:
 - » Complexity:
 - Insert / Delete O(1)
 - Find O(1)
 - Find neighbors
 O(|V|)
 - » Memory consumption:
 - Directed graph $O(|V|^2)$
 - Undirected graph $O(|V|^2 / 2)$
 - » Use case:
 - Small graphs due to simplicity and memory consumption
 - Dense graphs due to low complexity



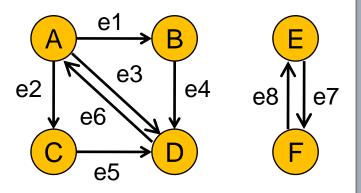
- Matrix structures:
 - Incidence matrix:

Is a matrix B of size |V| (number of vertices) by |E| (number of edges) with entries $b_{i,j}$ which indicate whether the vertex i incidence edge j.

- » Edge j enters vertex i: $b_{i,i} = 1$
- » Edge j leaves vertex i: $b_{i,j} = -1$
- » No incident: 0

Example:

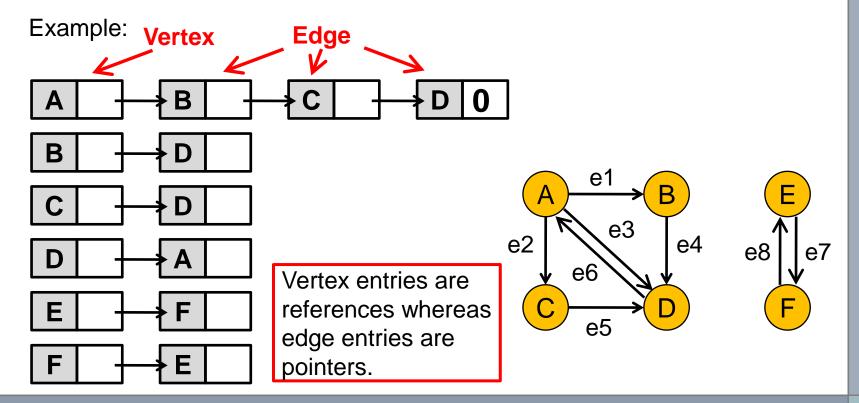
Vertex / Edge	e1	e2	e3	e4	e5	e6	e7	e8	e9
Α	-1	-1	-1	0	0	1	0	0	0
В	1	0	0	-1	0	0	0	0	0
С	0	1	0	0	-1	0	0	0	0
D	0	0	1	1	1	-1	0	0	0
E	0	0	0	0	0	0	-1	1	0
F	0	0	0	0	0	0	1	-1	0





- Linked structures:
 - Adjacency list:

Is an array/list of length |V| which holds for each node a list of its neighbor nodes.



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- Linked structures:
 - Adjacency list:
 - Characteristics:
 - » Complexity:

 Insert 	O(1)
– Delete	O(V)
- Find	O(V)

- Find neighbors O(1)
- » Memory consumption:
 - Directed graph O(|V|+|E|)
 - Undirected graph O(|V|+2|E|)
- » Use case:
 - Sparse graphs
 - Efficient if neighbor nodes have to be found frequently



□ Special Case:

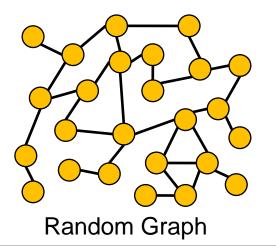
Scale-free graph:

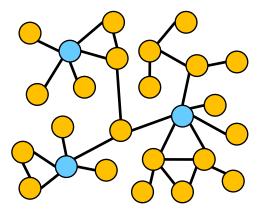
A graph is called scale-free if its node degree k follows the power law.

 $P(k) = ck^{-\gamma}$

c and γ are constants. Typical range 0 < c < 1, 2 < γ < 3.

- Examples:
 - Social networks
 - Collaboration networks
 - Computer networks
 - Disease transmission





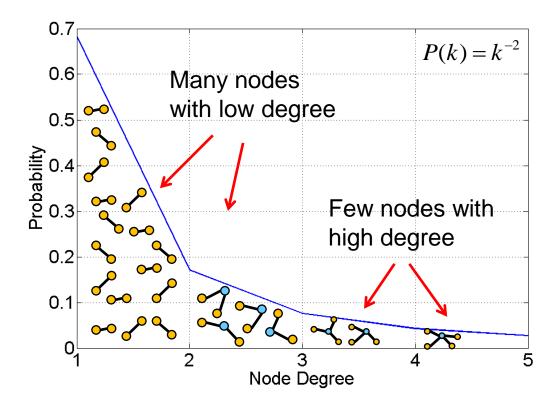
Scale-free Graph



- □ Special Case:
 - Scale-free graph:

Characteristics:

- High number of nodes with a small node degree.
- Small number of nodes (hubs) with a high node degree.





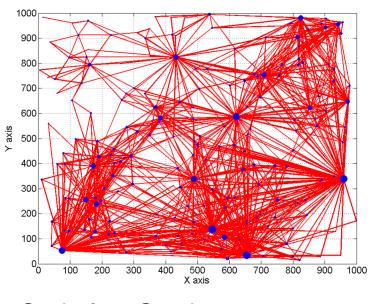
Special Case:

Scale-free graph:

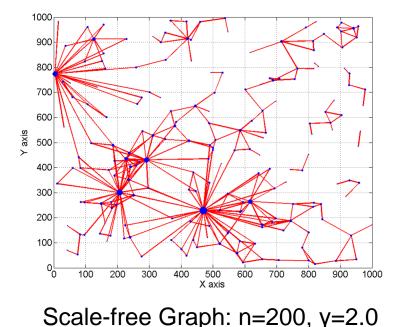
A graph is called scale-free if its node degree k follows the power law.

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c and γ are constants. Typical range 0 < c < 1, 2 < γ < 3.



Scale-free Graph: n=200, y=1.5



Examples:



- □ Scale-free networks real-world examples:
 - Six degrees of separation:
 - Small-world phenomenon:

Experiment by Stanley Milgram (1967)

- » Give letters to approx. 100 participants which should forward their letter to a specific person they do not know personally. Also the address of the person is not known.
- » The participants where only allowed to forward the letter by hand to a person, which they think, could forward it more closer to the destination.
- » The letters reached the destination via a maximum of 6 people.
- » Experiment was repeated and confirmed several times with sender and receiver even being part of different ethnological groups.



Everybody on this planet is separated only by six other people.



- □ Scale-free networks real-world examples:
 - Kevin Bacon Game and the movie actor network :
 - The Kevin Bacon Number defines the separation of movie actors away from Kevin Bacon.
 - One actor has distance 0 (Kevin Bacon himself).1902 actors have distance 1 since they played in a movie starring Kevin Beacon.
 160463 actors have distance 2 since they played in movie in which someone played who played in a movie starring Kevin Bacon.

Kevin Bacon Number	Number of Actors
0	1
1	1902
2	160463
3	457231
4	111310
5	8168
6	810
7	81
8	14

 Kevin Bacon seems to be the reasonable center of the network.



- □ Scale-free networks real-world examples:
 - Kevin Bacon Game and the movie actor network :
 - Kevin Bacon is only the 1049th best center out of nearly 800.000 movie actors. This makes make Kevin Bacon a better center than 99% of the actors.
 - However, there are still some better centers, like Sean Connery due to his higher first and second degree.

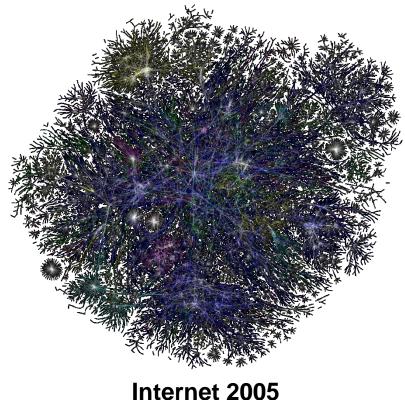
VS.

Kevin	Number
Bacon	of
Number	Actors
0	1
1	1902
2 3	160463
3	457231
4	111310
5	8168
6	810
7	81
8	14

Sean	Number			
Connery Number	of Actors			
0	1			
1	2272			
2	218560			
3	380721			
4	40263			
5	3537			
6	535			
7	66			
8	2			



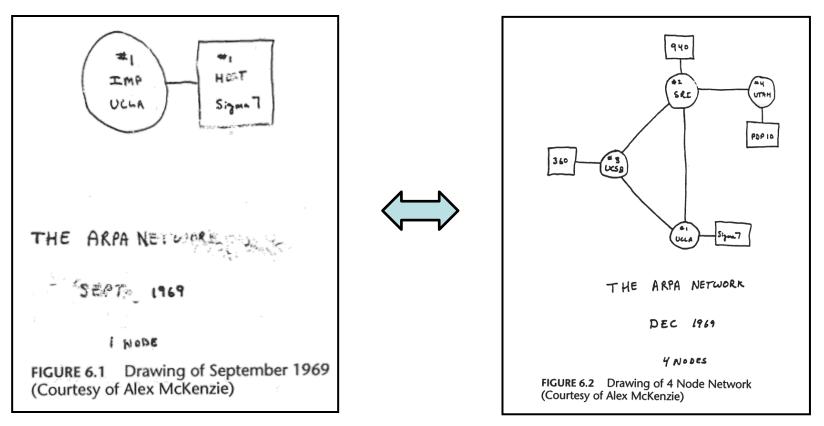
- □ Scale-free networks real-world examples:
 - The Internet:
 - The network diameter of the Internet is shorter than expected.
 - The maximum number of hops of a loop free path is approximately 30 hops.



Picture taken from http://www.opte.org



The Internet



ARPANET September 1969

ARPANET December 1969

The Internet was a success story already from the beginning where it increased its size within 3 months by a factor of four!

Pictures taken from http://www.cybergeography.org/atlas/historical.html



- □ Scale-free networks real-world examples:
 - Social networks Facebook:



Facebook Friendships

Picture taken from http://www.opte.org